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shows that $v=4v^3 \ 0 \ u.$

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$D(q^{-1})A(q^{-1})[-T(t) \quad (t \sim +1)]$ (3.161) and the parameter adaptation algorithm satisfying the passivity condition will take the form: $(t \hat{$

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$+1) = (t)^{\wedge} + F(t) (t+1)$ (3.162) The equivalent feedback representation associated with the output error predictor using the above PAA is shown in Fig. 3.9.

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